**PROJECT MANAGEMENT GANTT CHART TEMPLATE**

MILESTONE 5:

Mocking/Testing of Controller

MILESTONE 1:

Complete G-code Interpreter and motion planner

MILESTONE 3:

Complete SD Card Interface

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| PROJECT NAME |
| *STM32 Based Touch Screen CNC Controller* |

MILESTONE 4:

Complete Hardware Design and build

MILESTONE 2:

Complete Integration with microcontroller

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| PROJECT MANAGER |
| Jay Webb |

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| PROJECT START DATE | PROJECT END DATE | TODAY’S DATE |
| 01/10/2023 | 02/05/2024 |  |

Individual columns represent weeks.

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|  |  |  |  |  | **MONTH** | | **10** | **10** | **11** | **11** | **11** | **11** | **12** | **12** | **12** | **12** | **1** | **1** | **1** | **1** | **1** | **2** | **2** | **2** | **2** | **3** | **3** | **3** | **3** | **4** | **4** | **4** | **4** | **4** |
|  |  |  |  |  | **WEEK START DATE** | | **23** | **30** | **6** | **13** | **20** | **27** | **4** | **11** | **18** | **25** | **1** | **8** | **15** | **22** | **29** | **5** | **12** | **19** | **26** | **4** | **11** | **18** | **25** | **1** | **8** | **15** | **22** | **29** |
| **WBS** | **TASK TITLE** | **TASK DESCRIPTION** | **% DONE** | **TASK OWNER** | **START DATE** | **END DATE** | **1** | **2** | **3** | **4** | **5** | **6** | **7** | **8** | **9** | **10** | **11** | **12** | **13** | **14** | **15** | **16** | **17** | **18** | **19** | **20** | **21** | **22** | **23** | **24** | **25** | **26** | **27** | **28** |
| **1.0** | **Write G-code interpreter and motion planner** |  |  |  | **11/2023** | **01/2024** |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 1.1 | Design workflow of interpreter and motion planner | Design flow-chart/block-diagram and pseudo-code for interpreter and motion planner |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 1.2 | Write G-code Interpreter |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 1.3 | Test G-code Interpreter |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 1.4 | Write Motion planner |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 1.5 | Test motion planner within Matlab | Test to see how well the motion planning works |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| **2.0** | **Integrate in microcontroller** |  |  |  | **01/2024** | **03/2024** |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 2.1 | Design system workflow | Design flow-chart/block diagram of entire system |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 2.2 | Write Pin map | Define the pins and their uses |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 2.3 | Write UART code | Write code to configure the UART for communication with the PC |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 2.4 | Write jogging buttons code | Write code that allows use of the buttons to jog each axis |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 2.5 | Write limit switch, coolant control and tool probe code | Write code that configures the limit switches, coolant and tool probe |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 2.6 | Integrate interpreter and motion planning | Integrate with the system to allow G-code to be sent from PC and translated into corresponding motions |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 2.7 | Write PWM code | Write code that generates PWM signals to control the motors |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 2.8 | Test Code | Test entire code as a system |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |

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| **3.0** | **Write SD Card Interface** |  |  | **Jay Webb** | **03/2024** | **03/2024** |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 3.1 | Design SD card workflow | Design the workflow for the SD card interface and how it will integrate with Grbl |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 3.2 | Write SD Interface code | Write the SD card interface code |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 3.3 | Integrate code with System |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 3.4 | Test Code | Test the SD code by trying to load a simple gcode file |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| **4.0** | **Design PCB Controller** |  |  | **Jay Webb** | **03/2024** | **04/2024** |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 4.1 | Draw General schematic | Draw the schematic of the controller without any specific values for resistors or capacitors, using Proteus |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 4.2 | Calculate specific component values | Calculate component values and add them to schematic |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 4.3 | Test using breadboards | Test schematic using breadboards to ensure everything works as intended |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 4.4 | Design PCB layout | Design the corresponding PCB for the schematic using Proteus and prepare file for PCB production |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 4.5 | Assemble PCB | Once PCB has been produced, solder and assemble the controller with the components |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 4.6 | Test Controller | Test the assembled controller by connecting using the USB and sending Grbl commands using terminal |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| **5.0** | **Integrate Controller With CNC Test Rig** |  |  | **Jay Webb** | **21/04/24** | **28/04/24** |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 5.1 | Make connections from controller to CNC | Connect limit switches and motors on CNC to the controller |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 5.2 | Enter the machine parameters into controller | Enter parameters such as table size, hard limits enabled, motor parameters etc |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 5.3 | Test G-code for correct operation | Test Gcode and ensure correct movement to corresponding gcode |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 5.4 | Configure homing sequence on controller for demo | Configure homing sequence, auto enabling the limit switches and then ‘backing off’ a specified distance |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| **6.0** | **Project Management** |  |  | **Jay Webb** | **10/2023** | **1/05/24** |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 6.1 | Initial Research |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 6.2 | Project Proposal |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 6.3 | Risk Assessment | Complete Risk assessment for the project |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 6.4 | Background Research |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 6.5 | Order Components |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 6.6 | Report | Write the project the report |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 6.7 | Video | Create video for the project |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 6.8 | Poster | Design a poster for the project |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |